

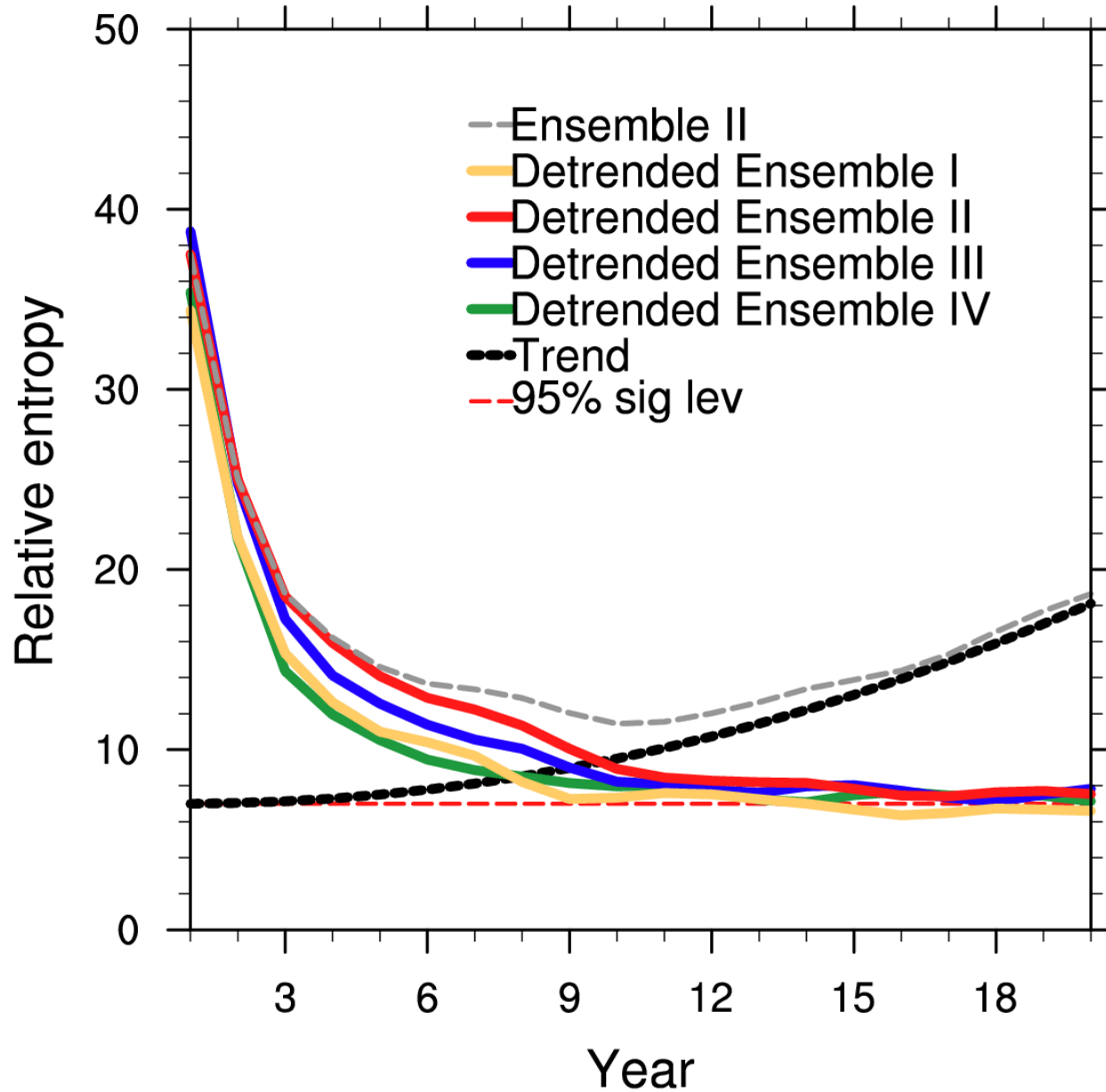
# **Initial-value Predictability of Prominent Modes of North Pacific Subsurface Temperature in a CGCM**

**Haiyan Teng and Grant Branstator**

**NCAR CGD**

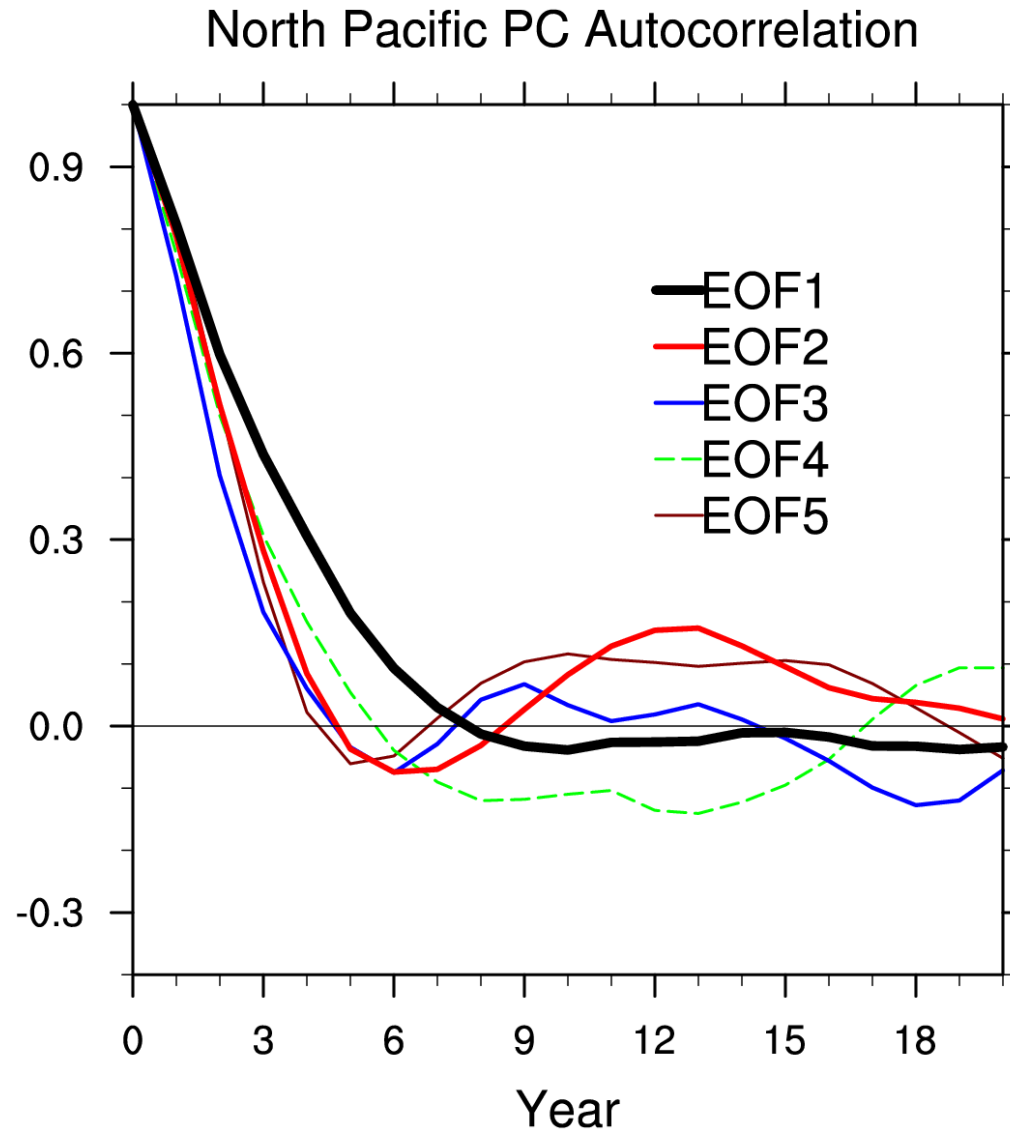
*Decadal workshop, Harbortowne, MD, Oct 15th, 2009*

# Global Domain EOF1-25



*Branstator talk,  
yesterday*

# Why are we interested in the prominent modes?



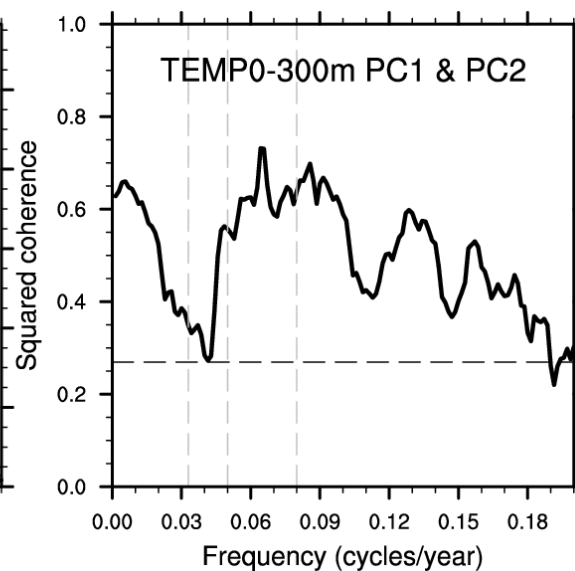
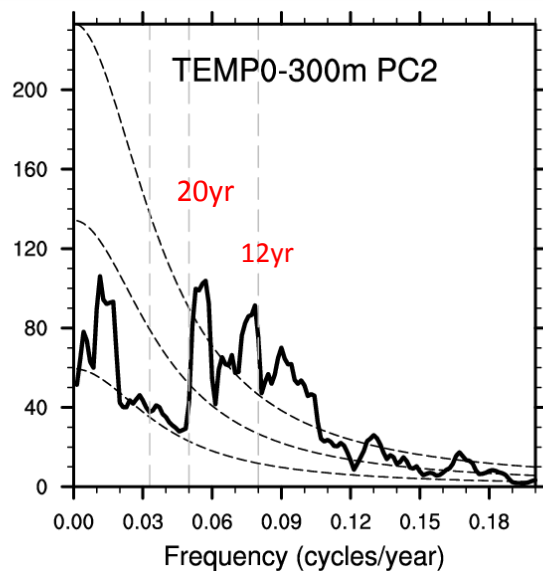
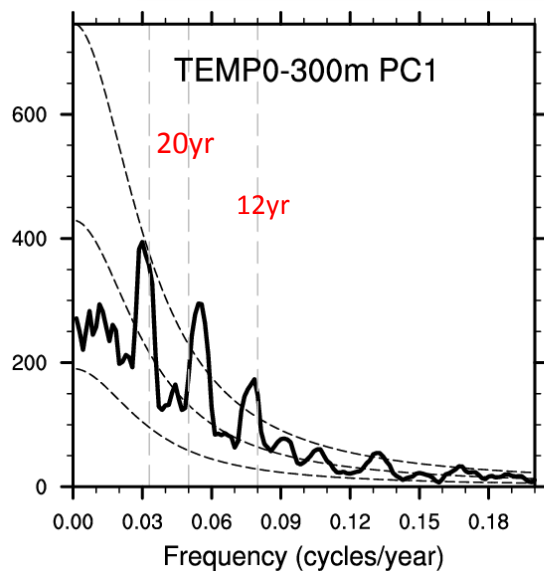
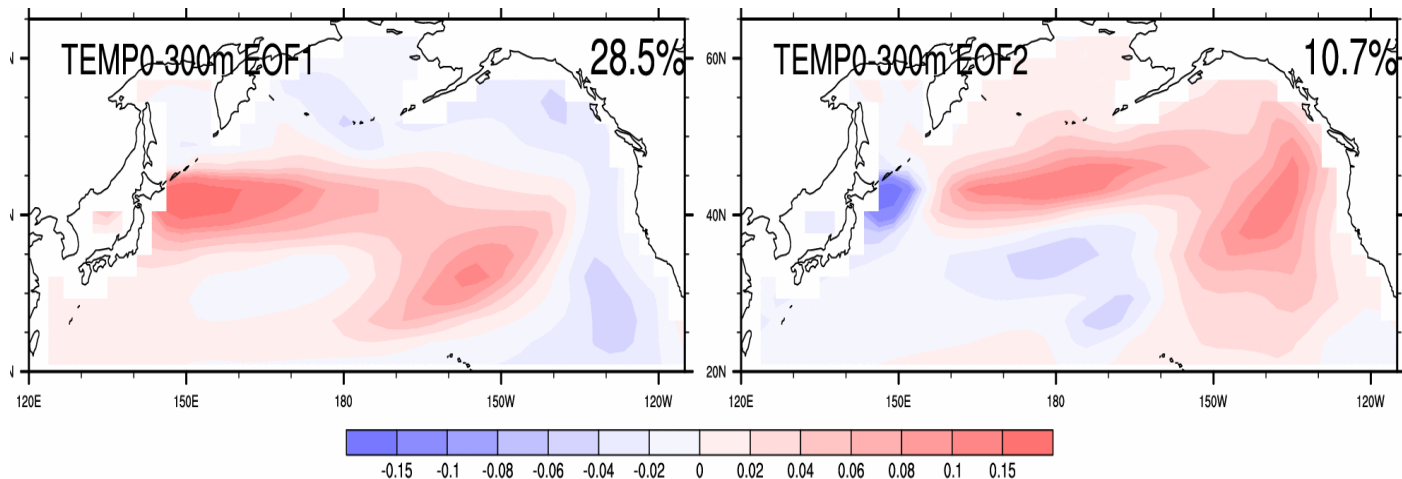
# Questions

- *To what extent is there predictability in the prominent modes in the subsurface temperature?*
- *How much do the prominent modes contribute to the predictability of the entire North Pacific region?*

# Experiments

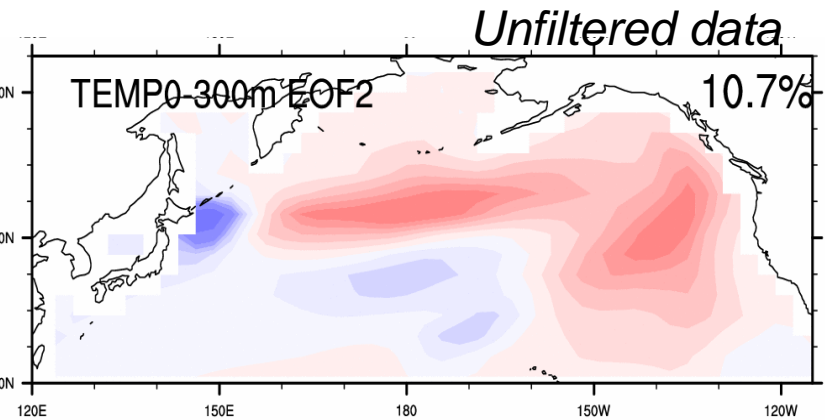
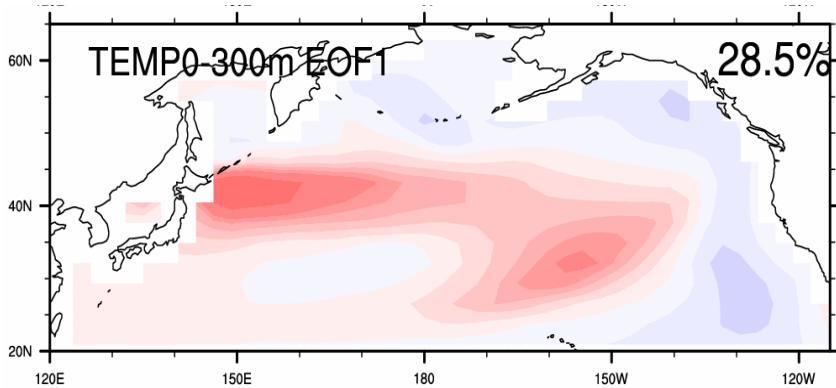
CCSM3 Experiments	Period	External forcing	Initial perturbation	Initial ocean state
<b>Present-day control</b>	0300-0999	control		
<b>Ensemble I (40 members)</b>	2000-2061	SRES A1B	Different atm/ same ocn, ice, Ind	Close to neutral EOF1(PDO)
<b>Ensemble II (40 members)</b>	2008-2028	SRES A1B	Infinitesimal differences in the solar constant	Very warm EOF1(PDO )
<b>Ensemble III (40 members)</b>	2008-2028	SRES A1B	Infinitesimal differences in the solar constant	Warm EOF2, weak EOF1(PDO)

# Leading EOF Modes

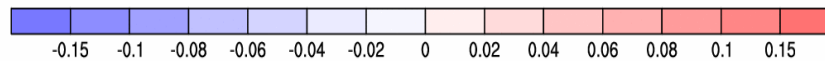
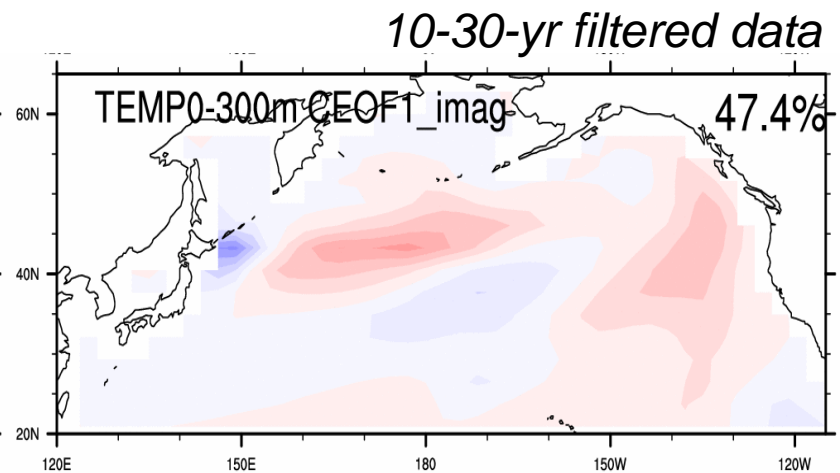
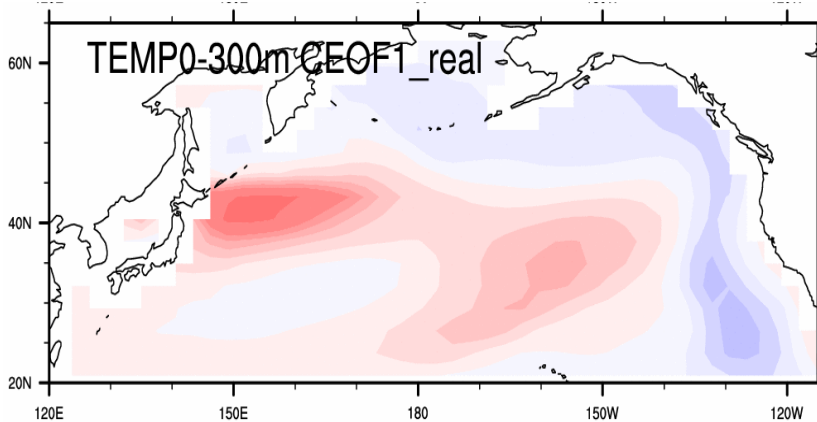


*From 700-yr control*

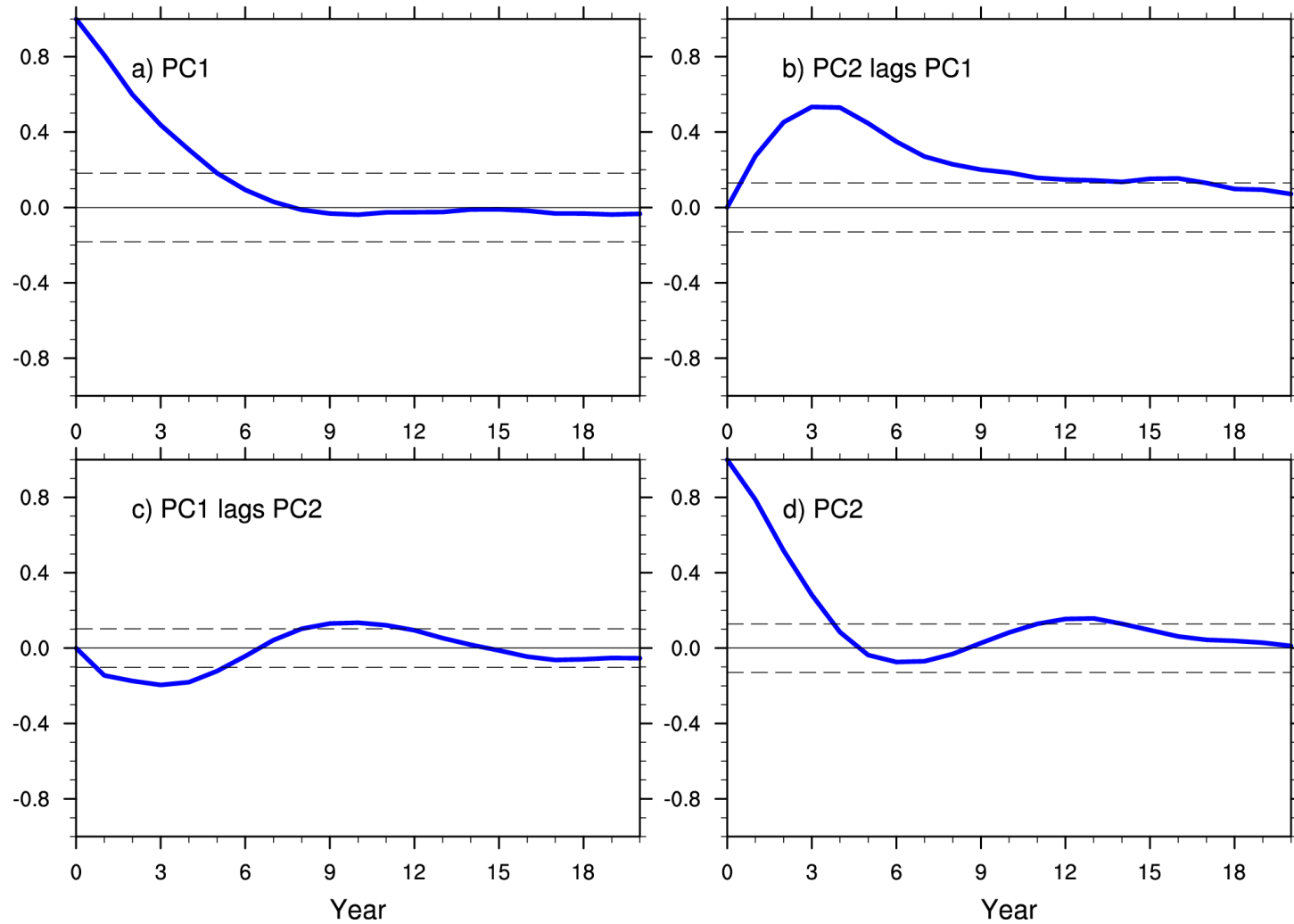
# EOF1,2



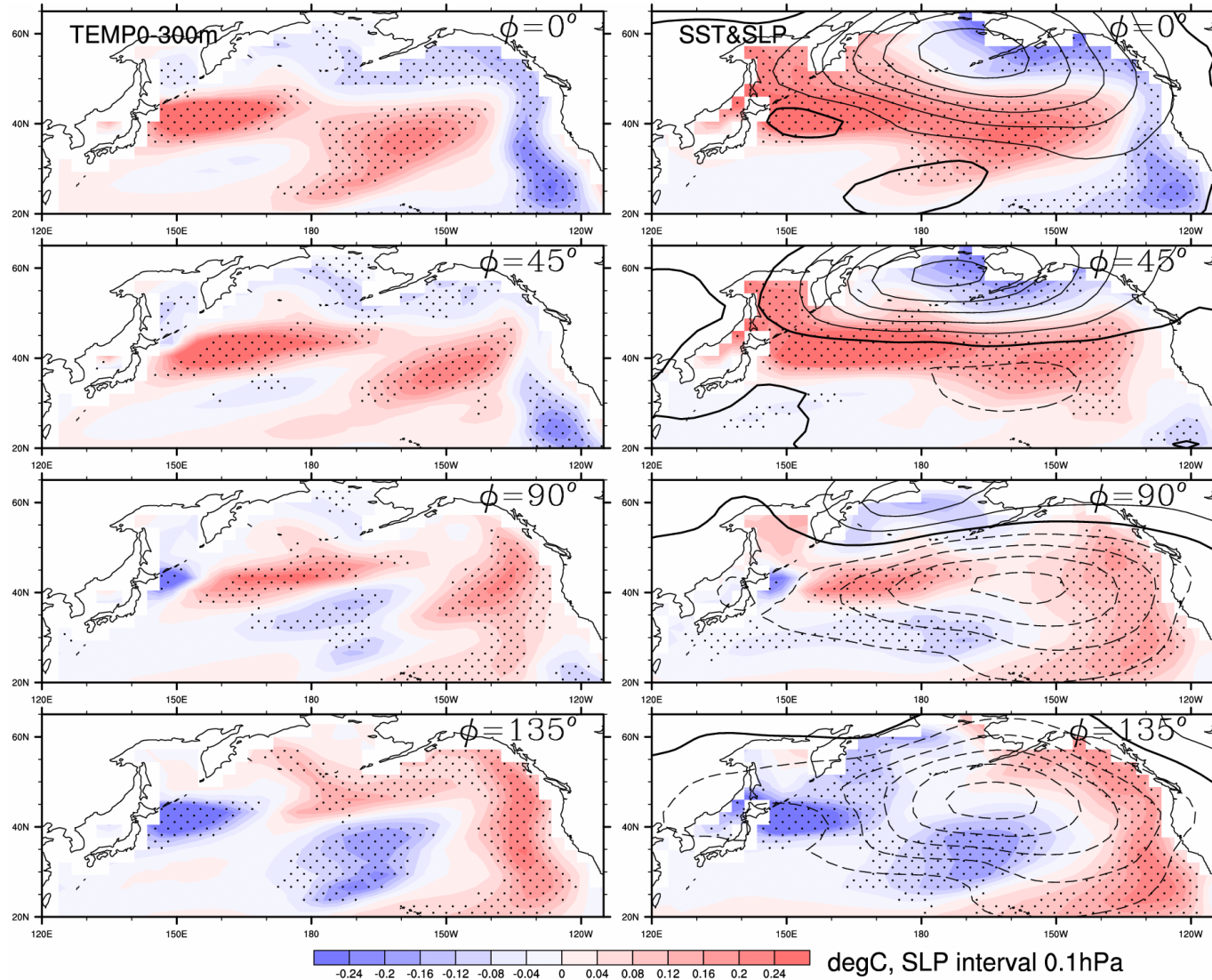
# CEOF1



# Lag and autocorrelations of the leading PCs



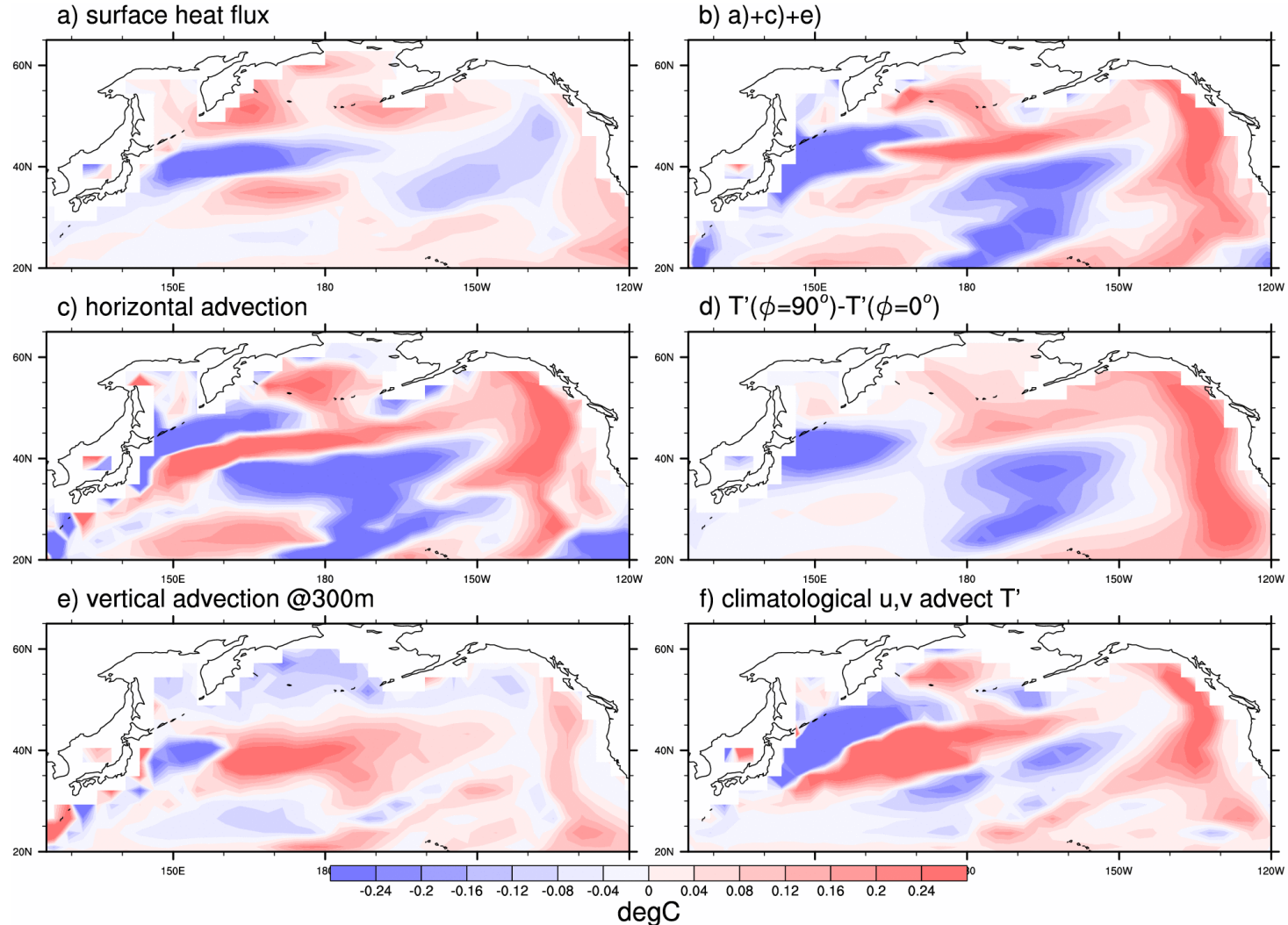
# Evolution of Subsurface Temperature CEOF1 & SST, SLP



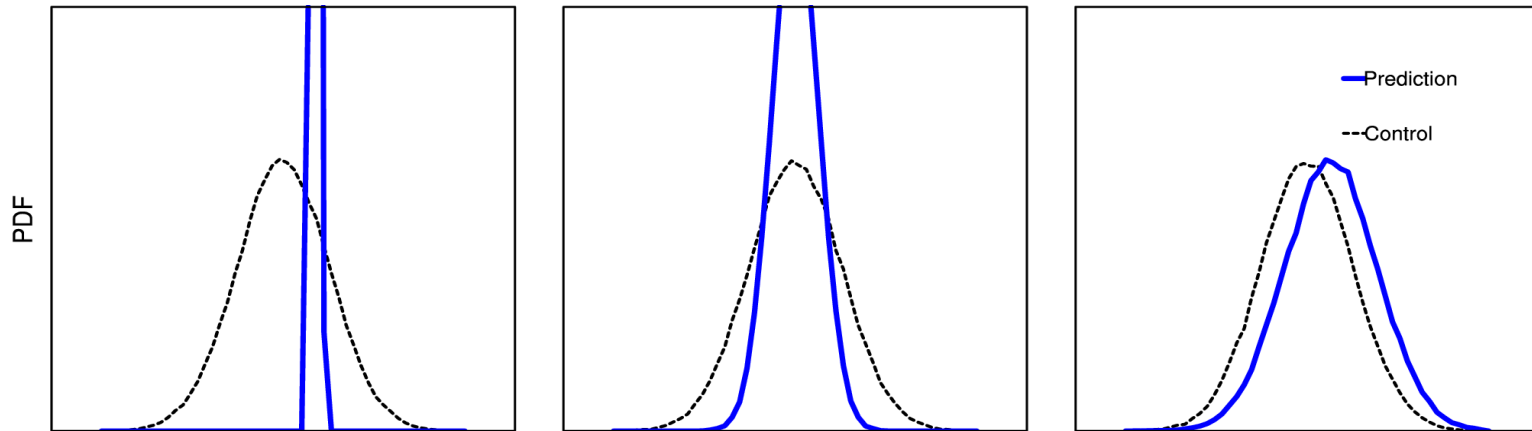
*composite based on 10-30-yr filtered data, ~ 60 episodes in 700-yr control*

# Heat Budget Analysis of the leading propagating mode

$$\frac{\partial T}{\partial t} = -\frac{Q_{net}}{\rho_0 C_p H} - \left( u \frac{\partial T}{\partial x} + v \frac{\partial T}{\partial y} \right) - w \frac{\partial T}{\partial z} \Big|_{z=300m}$$



# Measure of Predictability: Relative Entropy



*Kleeman (2002)*

$$R = \sum_i p_i \ln\left(\frac{p_i}{q_i}\right) \quad p_i: \text{Prediction}, \quad q_i: \text{Climatological distribution}$$

*For normal distribution:*

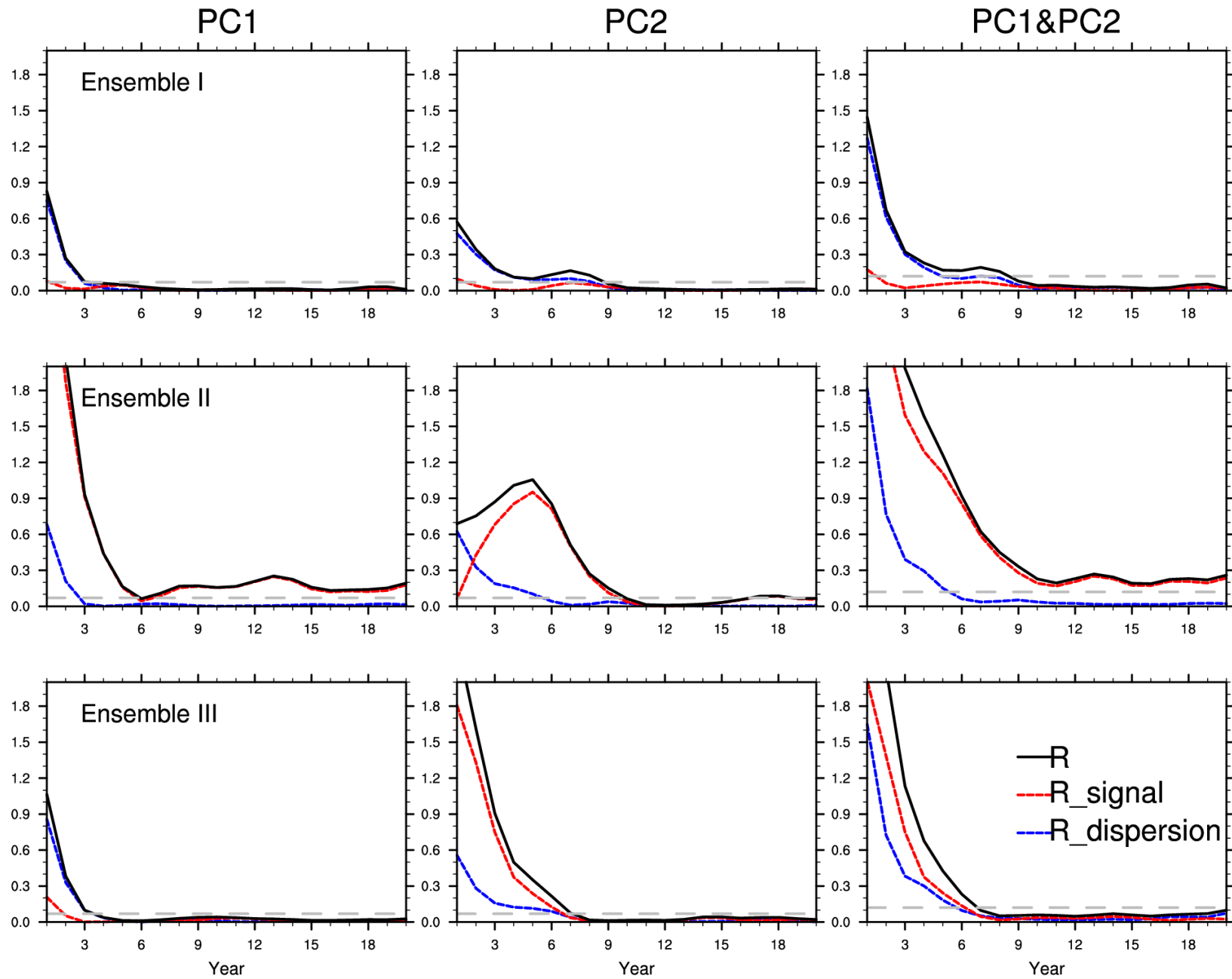
$$R_1 = \frac{1}{2} \left[ \ln\left(\frac{\sigma_c^2}{\sigma_e^2}\right) + \frac{\sigma_e^2}{\sigma_c^2} + \frac{(\mu^e - \mu^c)^2}{\sigma_c^2} - 1 \right]$$

$$R_n = \frac{1}{2} \left\{ \ln\left[ \frac{\det(\sigma_c^2)}{\det(\sigma_e^2)} \right] + \text{tr}[\sigma_e^2(\sigma_c^2)^{-1}] + (\vec{\mu}^e - \vec{\mu}^c)^t (\sigma_c^2)^{-1} (\vec{\mu}^e - \vec{\mu}^c) - n \right\}$$

**dispersion**

**signal**

# Relative Entropy of the Leading PCs



# Predictability Estimated from a Linear Stochastic Model

## Linear Inverse Model (LIM)

Penland (1989)

$$\frac{d\mathbf{X}}{dt} = \mathbf{B}\mathbf{X} + \xi$$

$$\mathbf{X}(t + \tau) = e^{\mathbf{B}\tau} \mathbf{X}(t)$$

$$\mathbf{B} = \tau_0^{-1} \ln\{\mathbf{C}(\tau_0)\mathbf{C}(0)^{-1}\}$$

$$\mathbf{C}(\tau_0) = \langle \mathbf{X}(t + \tau_0)\mathbf{X}^T(t) \rangle$$

$$\mathbf{C}(0) = \langle \mathbf{X}(t)\mathbf{X}^T(t) \rangle$$

$$\mathbf{G} \equiv \exp(\mathbf{B}\tau) = [\mathbf{G}(\tau_0)]^{\tau/\tau_0}$$

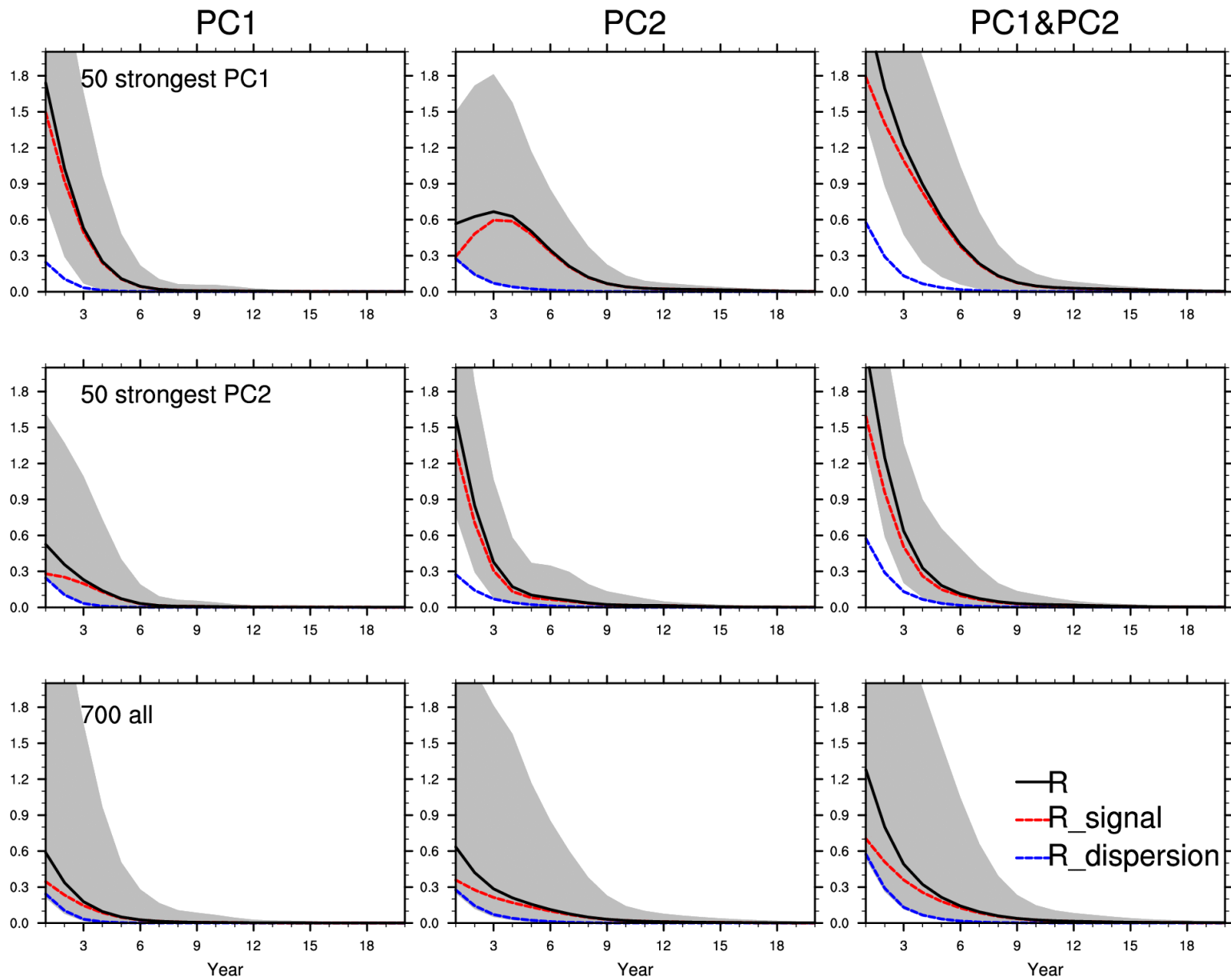
- For initial state  $\tilde{\mathbf{X}}(t)$ , forecasts at  $t+\tau$  has mean

$$\bar{\mathbf{X}}(t + \tau) = \mathbf{G}(\tau)\tilde{\mathbf{X}}(t)$$

and covariance

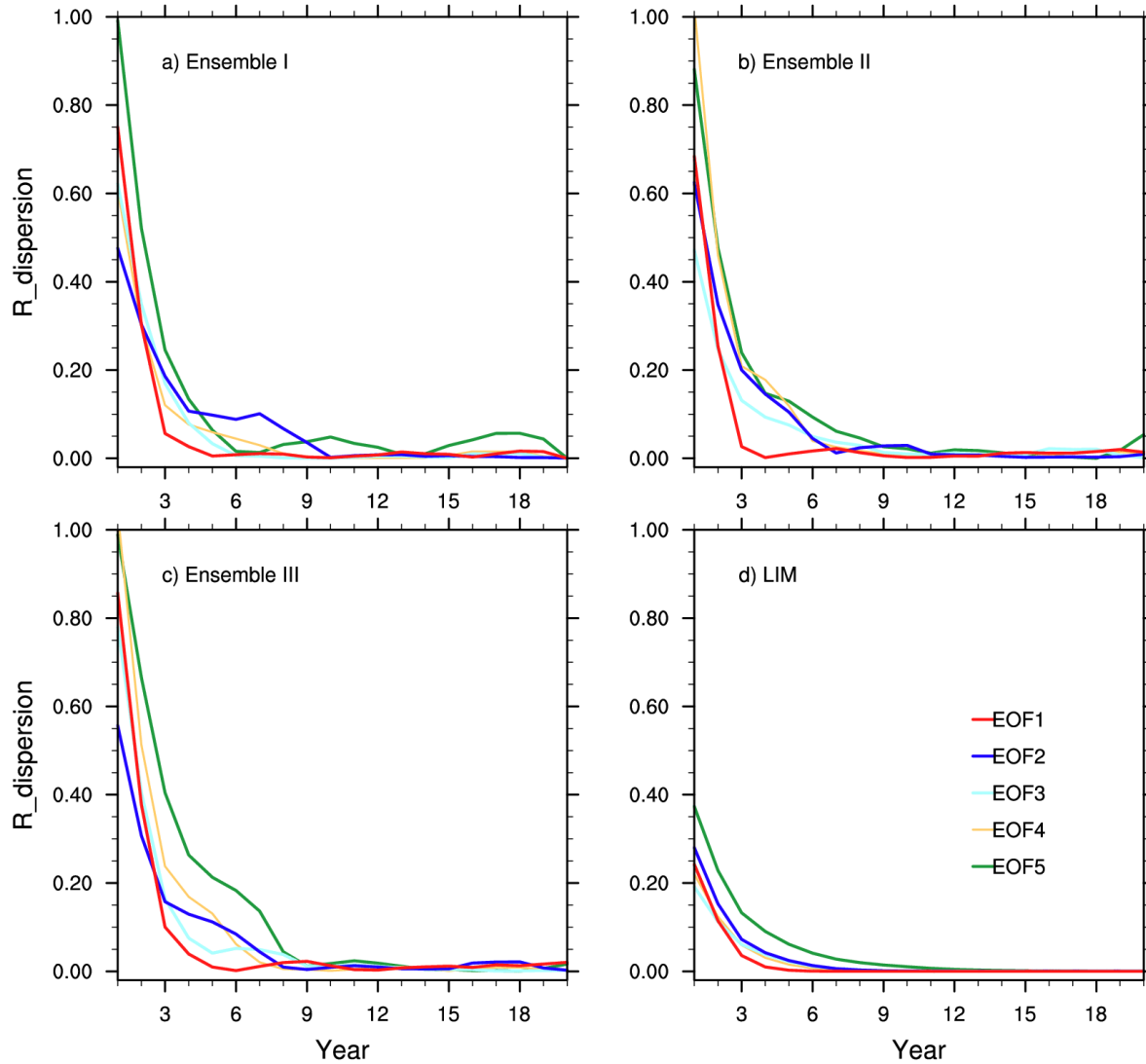
$$\langle \mathbf{X}(t + \tau)\mathbf{X}^T(t + \tau) \rangle = \mathbf{C}(0) - \mathbf{G}(\tau)\mathbf{C}(0)\mathbf{G}^T(\tau)$$

# Relative Entropy of the Leading PCs from LIM



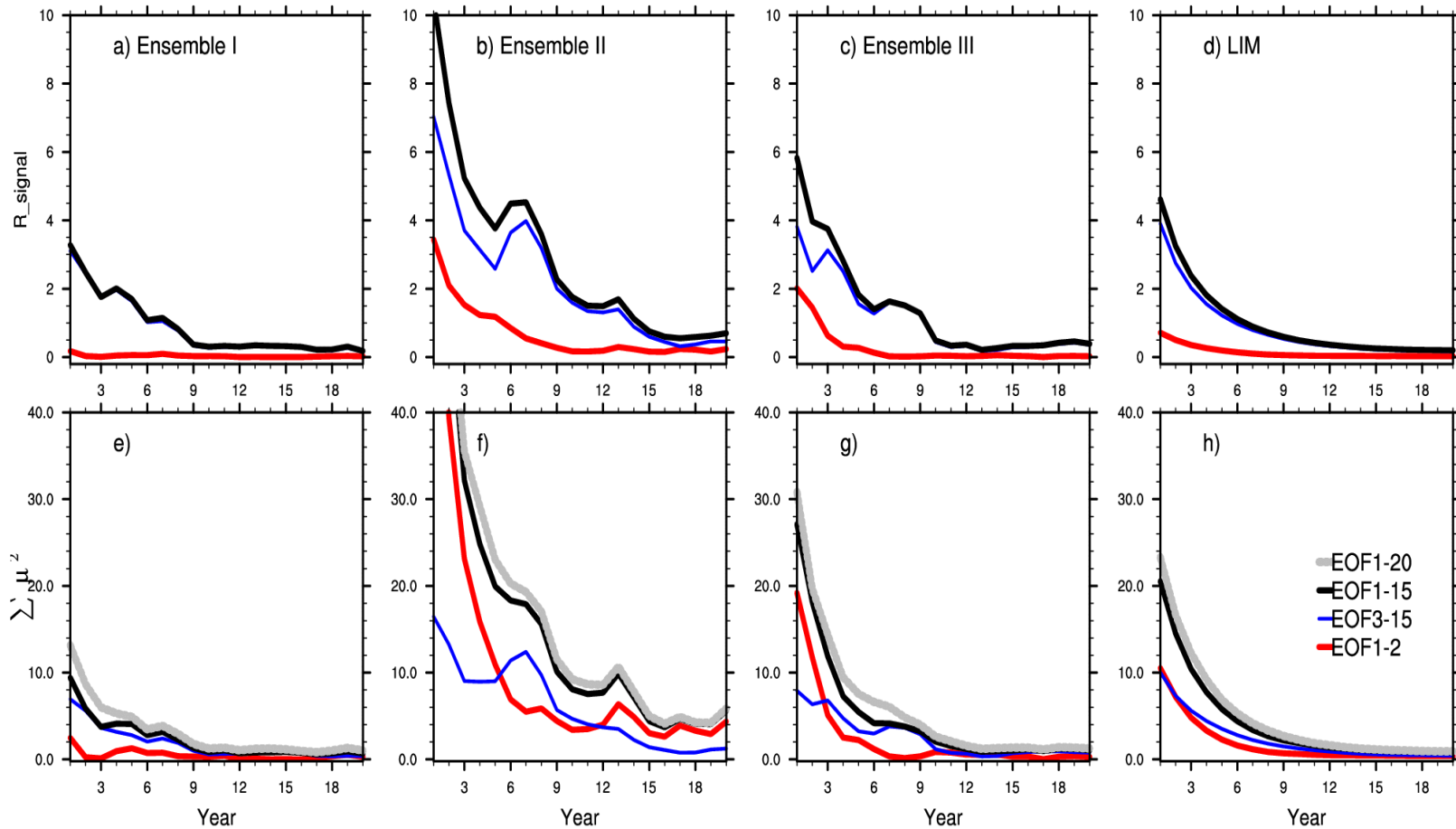
# Dispersion Component of Relative Entropy of the Leading PCs

$$R_1 = \frac{1}{2} \left[ \ln\left(\frac{\sigma_c^2}{\sigma_e^2}\right) + \frac{\sigma_e^2}{\sigma_c^2} + \frac{\mu_e^2}{\sigma_c^2} - 1 \right]$$

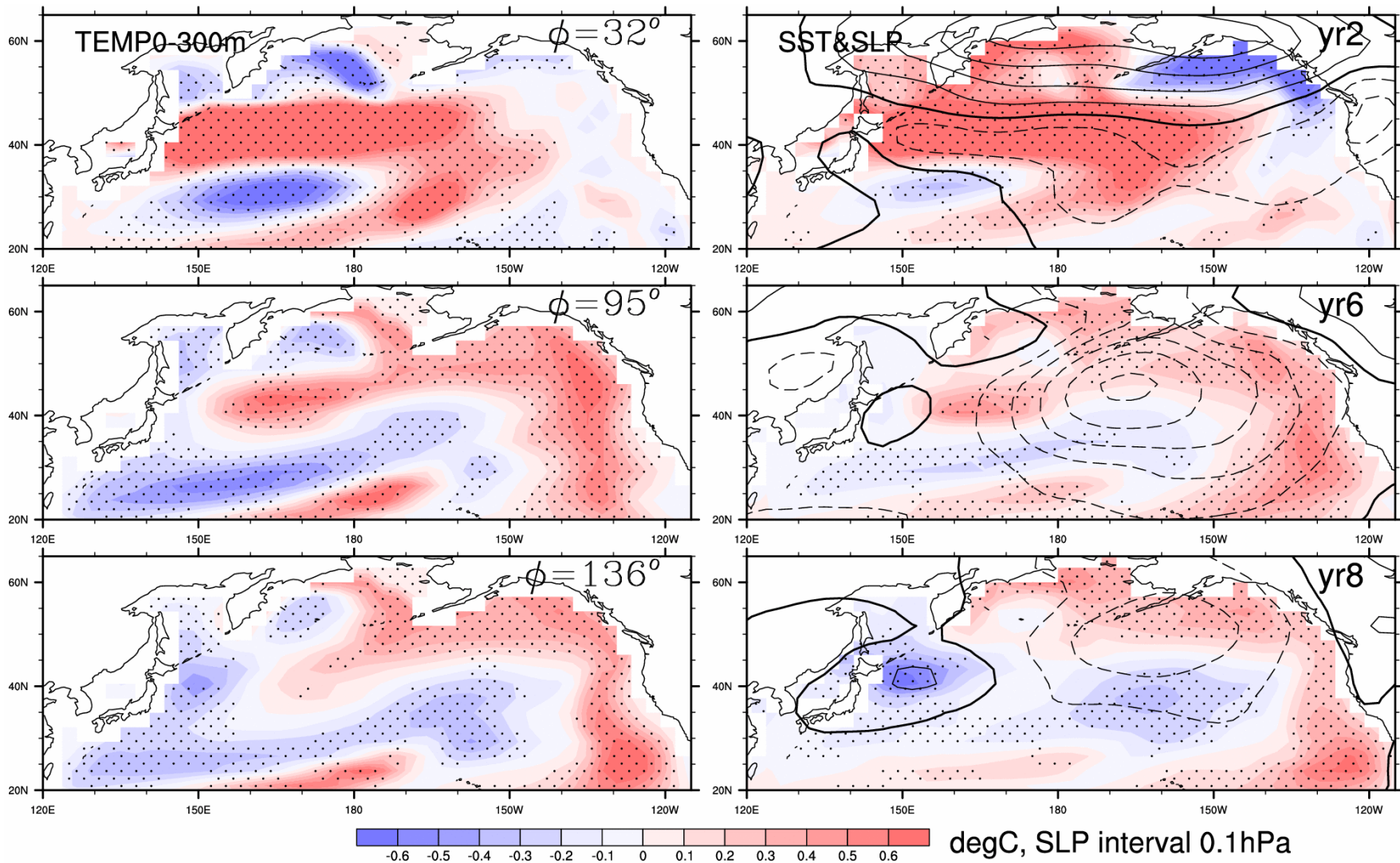


# Signal Component of Relative Entropy of the Leading PCs

$$R_n = \frac{1}{2} \left\{ \ln \left[ \frac{\det(\sigma_c^2)}{\det(\sigma_e^2)} \right] + \text{tr}[\sigma_e^2 (\sigma_c^2)^{-1}] + (\mu^e - \mu^c)^T (\sigma_c^2)^{-1} (\mu^e - \mu^c) - n \right\}$$



# Subsurface Temperature, SST, and 10-30-yr SLP in Ensemble II



# Lessons

- The **intrinsic time scale** of a pattern is **not necessarily a good indicator** of its predictability.
- Allow for **time evolving modes** when examining predictability.
- Both the **mean and spread** of an ensemble should be taken into account when assessing initial-value predictability.